

Non-smooth contact phenomena and surface damage

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The model

The physical problem
The damage phenomenon
The adhesion
phenomenon [Frémond
Internal constraints
Unilateral conditions

The PDE system

The PDE: the momentum
balance
The PDE: the evolution of
the damage
(micro-motions)
The PDE: the evolution of
the adhesion
(micro-motions)

Analytical results

Difficulties
Existence result

Asymptotic analysis

The problem
The analysis
Ideas and Perspectives

The problem

Damage vs. adhesion

**Non-smooth
contact
phenomena and
surface damage**

**E. Bonetti - M.
Frémond**

The model

The physical problem

The damage phenomenon

The adhesion
phenomenon [Frémond

Internal constraints

Unilateral conditions

The PDE system

The PDE: the momentum
balance

The PDE: the evolution of
the damage
(micro-motions)

The PDE: the evolution of
the adhesion
(micro-motions)

Analytical results

Difficulties

Existence result

Asymptotic analysis

The problem

The analysis

Ideas and Perspectives

The problem

Damage vs. adhesion

interfaces and discontinuities

**Non-smooth
contact
phenomena and
surface damage**

**E. Bonetti - M.
Frémond**

The model

The physical problem

The damage phenomenon

The adhesion
phenomenon [Frémond]

Internal constraints

Unilateral conditions

The PDE system

The PDE: the momentum
balance

The PDE: the evolution of
the damage
(micro-motions)

The PDE: the evolution of
the adhesion
(micro-motions)

Analytical results

Difficulties

Existence result

Asymptotic analysis

The problem

The analysis

Ideas and Perspectives

The problem

Damage vs. adhesion

interfaces and discontinuities

analytical description by use of phase transitions

- ▶ in domains: losing rigidity

Non-smooth
contact
phenomena and
surface damage

E. Bonetti - M.
Frémond

The model

The physical problem

The damage phenomenon

The adhesion
phenomenon [Frémond]

Internal constraints

Unilateral conditions

The PDE system

The PDE: the momentum
balance

The PDE: the evolution of
the damage
(micro-motions)

The PDE: the evolution of
the adhesion
(micro-motions)

Analytical results

Difficulties

Existence result

Asymptotic analysis

The problem

The analysis

Ideas and Perspectives

The problem

Damage vs. adhesion

interfaces and discontinuities

analytical description by use of phase transitions

- ▶ in domains: losing rigidity
- ▶ on surfaces: theory of the adhesion between bodies

Non-smooth
contact
phenomena and
surface damage

E. Bonetti - M.
Frémond

The model

The physical problem

The damage phenomenon

The adhesion
phenomenon [Frémond]

Internal constraints

Unilateral conditions

The PDE system

The PDE: the momentum
balance

The PDE: the evolution of
the damage
(micro-motions)

The PDE: the evolution of
the adhesion
(micro-motions)

Analytical results

Difficulties

Existence result

Asymptotic analysis

The problem

The analysis

Ideas and Perspectives

The problem

Damage vs. adhesion

interfaces and discontinuities

analytical description by use of phase transitions

- ▶ **in domains**: losing rigidity
- ▶ **on surfaces**: theory of the adhesion between bodies
- ▶ **fractures**: damage energy concentrated on surfaces
... how to relate?

Non-smooth
contact
phenomena and
surface damage

E. Bonetti - M.
Frémond

The model

The physical problem

The damage phenomenon

The adhesion
phenomenon [Frémond]

Internal constraints

Unilateral conditions

The PDE system

The PDE: the momentum
balance

The PDE: the evolution of
the damage
(micro-motions)

The PDE: the evolution of
the adhesion
(micro-motions)

Analytical results

Difficulties

Existence result

Asymptotic analysis

The problem

The analysis

Ideas and Perspectives

The problem

We describe **damage**

**Non-smooth
contact
phenomena and
surface damage**

**E. Bonetti - M.
Frémond**

The model

The physical problem

The damage phenomenon

The adhesion
phenomenon [Frémond

Internal constraints

Unilateral conditions

The PDE system

The PDE: the momentum
balance

The PDE: the evolution of
the damage
(micro-motions)

The PDE: the evolution of
the adhesion
(micro-motions)

Analytical results

Difficulties

Existence result

Asymptotic analysis

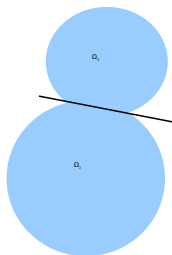
The problem

The analysis

Ideas and Perspectives

The problem

We describe **damage** in domains Ω_i which are in **contact with adhesion** on the surface Γ_c



Non-smooth contact phenomena and surface damage

E. Bonetti - M. Frémond

The model

The physical problem

The damage phenomenon

The adhesion phenomenon [Frémond]

Internal constraints

Unilateral conditions

The PDE system

The PDE: the momentum balance

The PDE: the evolution of the damage (micro-motions)

The PDE: the evolution of the adhesion (micro-motions)

Analytical results

Difficulties

Existence result

Asymptotic analysis

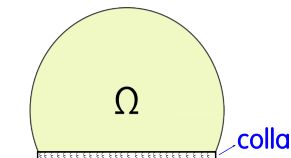
The problem

The analysis

Ideas and Perspectives

The problem

We describe **damage** for a domain Ω which is in **contact with adhesion** on a rigid support Γ_c (simplifying)



Non-smooth contact phenomena and surface damage

E. Bonetti - M. Frémond

The model

The physical problem

The damage phenomenon

The adhesion phenomenon [Frémond]

Internal constraints

Unilateral conditions

The PDE system

The PDE: the momentum balance

The PDE: the evolution of the damage (micro-motions)

The PDE: the evolution of the adhesion (micro-motions)

Analytical results

Difficulties

Existence result

Asymptotic analysis

The problem

The analysis

Ideas and Perspectives

The problem

We describe **damage** for a domain Ω which is in **contact with adhesion** on a rigid support Γ_c (simplifying)

- ▶ In the **volume domain Ω** :
 - ▶ **small deformations** ($\varepsilon(\mathbf{u})$ strain tensor)
 - ▶ **volume damage** (β phase parameter)
 - ▶ **thermal effects** (θ absolute temperature)
- ▶ On the **contact surface Γ_c** :
 - ▶ **adhesion** (χ phase parameter is related to the active bonds of the adhesion \rightarrow “damage parameter”)
 - ▶ **effects of displacement** ($\mathbf{u}|_{\Gamma_c}$ trace of the displacement) + **effects of volume damage** ($\beta|_{\Gamma_c}$ traces of volume damage variables)
 - ▶ **thermal effects** (θ_s absolute temperature)

Non-smooth contact phenomena and surface damage

E. Bonetti - M. Frémond

The model

The physical problem

The damage phenomenon
The adhesion phenomenon [Frémond]
Internal constraints
Unilateral conditions

The PDE system

The PDE: the momentum balance
The PDE: the evolution of the damage (micro-motions)
The PDE: the evolution of the adhesion (micro-motions)

Analytical results

Difficulties
Existence result

Asymptotic analysis

The problem
The analysis
Ideas and Perspectives

The damage phenomenon

Macroscopic description of a microscopic phenomenon:
changes in the micro-structure \rightarrow degenerating material
rigidity



phase transitions approach

Non-smooth
contact
phenomena and
surface damage

E. Bonetti - M.
Frémond

The model

The physical problem

The damage phenomenon

The adhesion
phenomenon [Frémond

Internal constraints

Unilateral conditions

The PDE system

The PDE: the momentum
balance

The PDE: the evolution of
the damage
(micro-motions)

The PDE: the evolution of
the adhesion
(micro-motions)

Analytical results

Difficulties

Existence result

Asymptotic analysis

The problem

The analysis

Ideas and Perspectives

The damage phenomenon

Macroscopic description of a microscopic phenomenon:
changes in the micro-structure \rightarrow degenerating material
rigidity



phase transitions approach

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bonds between particles of the material at each point in
the domain

Non-smooth
contact
phenomena and
surface damage

E. Bonetti - M.
Frémond

The model

The physical problem
The damage phenomenon
The adhesion
phenomenon [Frémond]
Internal constraints
Unilateral conditions

The PDE system

The PDE: the momentum
balance
The PDE: the evolution of
the damage
(micro-motions)
The PDE: the evolution of
the adhesion
(micro-motions)

Analytical results

Difficulties
Existence result

Asymptotic analysis

The problem
The analysis
Ideas and Perspectives

The damage phenomenon

Macroscopic description of a microscopic phenomenon:
changes in the micro-structure \rightarrow degenerating material rigidity



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the evolution of the damage is due to micro-motions and micro-forces (to be included in the energy balance)

Non-smooth contact phenomena and surface damage

E. Bonetti - M. Frémond

The model

The physical problem
The damage phenomenon
The adhesion phenomenon [Frémond]
Internal constraints
Unilateral conditions

The PDE system

The PDE: the momentum balance
The PDE: the evolution of the damage (micro-motions)
The PDE: the evolution of the adhesion (micro-motions)

Analytical results

Difficulties
Existence result

Asymptotic analysis

The problem
The analysis
Ideas and Perspectives

The damage phenomenon

Macroscopic description of a microscopic phenomenon:
changes in the micro-structure \rightarrow degenerating material rigidity



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- ▶ $\beta = 0$ complete damage

Non-smooth contact phenomena and surface damage

E. Bonetti - M. Frémond

The model

The physical problem
The damage phenomenon
The adhesion phenomenon [Frémond]
Internal constraints
Unilateral conditions

The PDE system

The PDE: the momentum balance
The PDE: the evolution of the damage (micro-motions)
The PDE: the evolution of the adhesion (micro-motions)

Analytical results

Difficulties
Existence result

Asymptotic analysis

The problem
The analysis
Ideas and Perspectives

The damage phenomenon

Macroscopic description of a microscopic phenomenon:
changes in the micro-structure \rightarrow degenerating material rigidity



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Non-smooth contact phenomena and surface damage

E. Bonetti - M. Frémond

The model

The physical problem
The damage phenomenon
The adhesion phenomenon [Frémond]
Internal constraints
Unilateral conditions

The PDE system

The PDE: the momentum balance
The PDE: the evolution of the damage (micro-motions)
The PDE: the evolution of the adhesion (micro-motions)

Analytical results

Difficulties
Existence result

Asymptotic analysis

The problem
The analysis
Ideas and Perspectives

The damage phenomenon

Macroscopic description of a microscopic phenomenon:
changes in the micro-structure \rightarrow degenerating material rigidity



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\rightarrow physical constraints

- ▶ $\beta \in [0, 1]$
- ▶ $\beta_t \leq 0$ (irreversible phenomenon)

Non-smooth contact phenomena and surface damage

E. Bonetti - M. Frémond

The model

The physical problem

The damage phenomenon

The adhesion phenomenon [Frémond]

Internal constraints

Unilateral conditions

The PDE system

The PDE: the momentum balance

The PDE: the evolution of the damage (micro-motions)

The PDE: the evolution of the adhesion (micro-motions)

Analytical results

Difficulties

Existence result

Asymptotic analysis

The problem

The analysis

Ideas and Perspectives

The damage phenomenon

Macroscopic description of a microscopic phenomenon:
changes in the micro-structure \rightarrow degenerating material rigidity



phase transitions approach

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\rightarrow non-smooth constraint in the evolution equation for β

Non-smooth contact phenomena and surface damage

E. Bonetti - M. Frémond

The model

The physical problem

The damage phenomenon

The adhesion phenomenon [Frémond]

Internal constraints

Unilateral conditions

The PDE system

The PDE: the momentum balance

The PDE: the evolution of the damage (micro-motions)

The PDE: the evolution of the adhesion (micro-motions)

Analytical results

Difficulties

Existence result

Asymptotic analysis

The problem

The analysis

Ideas and Perspectives

The adhesion phenomenon [Frémond]

We use a **surface damage model** by use of the **phase transitions approach**



a phase parameter χ denoting the **“proportion” of active bonds** at each point of the contact surface

Non-smooth contact phenomena and surface damage

E. Bonetti - M. Frémond

The model

The physical problem

The damage phenomenon

The adhesion phenomenon [Frémond]

Internal constraints

Unilateral conditions

The PDE system

The PDE: the momentum balance

The PDE: the evolution of the damage (micro-motions)

The PDE: the evolution of the adhesion (micro-motions)

Analytical results

Difficulties

Existence result

Asymptotic analysis

The problem

The analysis

Ideas and Perspectives

The adhesion phenomenon [Frémond]

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Non-smooth contact phenomena and surface damage

E. Bonetti - M. Frémond

The model

The physical problem
The damage phenomenon

The adhesion phenomenon [Frémond]

Internal constraints
Unilateral conditions

The PDE system

The PDE: the momentum balance

The PDE: the evolution of the damage (micro-motions)

The PDE: the evolution of the adhesion (micro-motions)

Analytical results

Difficulties
Existence result

Asymptotic analysis

The problem
The analysis
Ideas and Perspectives

The adhesion phenomenon [Frémond]

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Non-smooth contact phenomena and surface damage

E. Bonetti - M. Frémond

The model

The physical problem
The damage phenomenon

The adhesion phenomenon [Frémond]

Internal constraints
Unilateral conditions

The PDE system

The PDE: the momentum balance

The PDE: the evolution of the damage (micro-motions)

The PDE: the evolution of the adhesion (micro-motions)

Analytical results

Difficulties
Existence result

Asymptotic analysis

The problem
The analysis
Ideas and Perspectives

The adhesion phenomenon [Frémond]

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Non-smooth contact phenomena and surface damage

E. Bonetti - M. Frémond

The model

The physical problem
The damage phenomenon

The adhesion phenomenon [Frémond]

Internal constraints
Unilateral conditions

The PDE system

The PDE: the momentum balance

The PDE: the evolution of the damage (micro-motions)

The PDE: the evolution of the adhesion (micro-motions)

Analytical results

Difficulties
Existence result

Asymptotic analysis

The problem
The analysis
Ideas and Perspectives

The adhesion phenomenon [Frémond]

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→ **non-smooth constraint** in the evolution equation for χ

Non-smooth contact phenomena and surface damage

E. Bonetti - M. Frémond

The model

The physical problem
The damage phenomenon
The adhesion phenomenon [Frémond]
Internal constraints
Unilateral conditions

The PDE system

The PDE: the momentum balance
The PDE: the evolution of the damage (micro-motions)
The PDE: the evolution of the adhesion (micro-motions)

Analytical results

Difficulties
Existence result

Asymptotic analysis

The problem
The analysis
Ideas and Perspectives

Internal constraints

Non-smooth
contact
phenomena and
surface damage

E. Bonetti - M.
Frémond

To assure **physical consistency**: free energies and dissipation functionals includes internal constraints

$$\Psi_{\Omega} = \dots + I_{[0,1]}(\beta), \quad \Psi_{\Gamma_c} = \dots + I_{[0,1]}(\chi)$$

and (in the case of irreversible damage and/or adhesion evolution)

$$\Phi_{\Omega} = \dots + I_{(-\infty,0]}(\beta_t), \quad \Phi_{\Gamma_c} = \dots + I_{(-\infty,0]}(\chi_t)$$

The model

The physical problem
The damage phenomenon
The adhesion phenomenon [Frémond]
Internal constraints
Unilateral conditions

The PDE system

The PDE: the momentum balance
The PDE: the evolution of the damage (micro-motions)
The PDE: the evolution of the adhesion (micro-motions)

Analytical results

Difficulties
Existence result

Asymptotic analysis

The problem
The analysis
Ideas and Perspectives

Unilateral conditions

We have to ensure impenetrability between Ω and Γ_c i.e.

$$\mathbf{u}|_{\Gamma_c} \cdot \mathbf{n} \leq 0 \quad \text{in } \Gamma_c.$$

**Non-smooth
contact
phenomena and
surface damage**

**E. Bonetti - M.
Frémond**

The model

The physical problem
The damage phenomenon
The adhesion
phenomenon [Frémond
Internal constraints

Unilateral conditions

The PDE system

The PDE: the momentum
balance
The PDE: the evolution of
the damage
(micro-motions)
The PDE: the evolution of
the adhesion
(micro-motions)

Analytical results

Difficulties
Existence result

Asymptotic analysis

The problem
The analysis
Ideas and Perspectives

Unilateral conditions

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→ it is a **physical constraint** ensured by the reaction on the contact surface

**Non-smooth
contact
phenomena and
surface damage**

**E. Bonetti - M.
Frémond**

The model

The physical problem
The damage phenomenon
The adhesion
phenomenon [Frémond
Internal constraints

Unilateral conditions

The PDE system

The PDE: the momentum
balance
The PDE: the evolution of
the damage
(micro-motions)
The PDE: the evolution of
the adhesion
(micro-motions)

Analytical results

Difficulties
Existence result

Asymptotic analysis

The problem
The analysis
Ideas and Perspectives

Unilateral conditions

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In the case there is no adhesion $\chi = 0$ the reaction on Γ_c is

$$R = \chi \mathbf{u} + \partial h_{]-\infty, 0]}(\mathbf{u} \cdot \mathbf{n}) \mathbf{n}$$

i.e. we have the impenetrability condition as $\mathbf{u} \cdot \mathbf{n} \leq 0$ (cf. also Signorini conditions)

- ▶ R is normal to Γ_c
- ▶ $R = 0$ if $\mathbf{u} \cdot \mathbf{n} < 0$
- ▶ $R = \gamma \mathbf{n}$, $\gamma \geq 0$ if $\mathbf{u} \cdot \mathbf{n} = 0$ (avoiding $\mathbf{u} \cdot \mathbf{n}$ become positive)

The model

The physical problem
The damage phenomenon
The adhesion
phenomenon [Frémond
Internal constraints

Unilateral conditions

The PDE system

The PDE: the momentum
balance
The PDE: the evolution of
the damage
(micro-motions)
The PDE: the evolution of
the adhesion
(micro-motions)

Analytical results

Difficulties
Existence result

Asymptotic analysis

The problem
The analysis
Ideas and Perspectives

Unilateral conditions

We have to ensure impenetrability between Ω and Γ_c i.e.

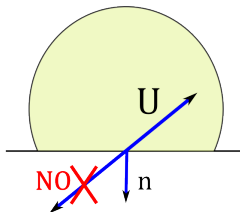
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The model

The physical problem
The damage phenomenon
The adhesion
phenomenon [Frémond
Internal constraints
Unilateral conditions

The PDE system

The PDE: the momentum
balance
The PDE: the evolution of
the damage
(micro-motions)
The PDE: the evolution of
the adhesion
(micro-motions)

Analytical results

Difficulties
Existence result

Asymptotic analysis

The problem
The analysis
Ideas and Perspectives

Unilateral conditions

We have to ensure impenetrability between Ω and Γ_c i.e.

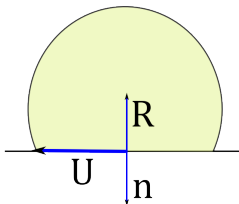
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The model

The physical problem
The damage phenomenon
The adhesion
phenomenon [Frémond
Internal constraints
Unilateral conditions

The PDE system

The PDE: the momentum
balance
The PDE: the evolution of
the damage
(micro-motions)
The PDE: the evolution of
the adhesion
(micro-motions)

Analytical results

Difficulties
Existence result

Asymptotic analysis

The problem
The analysis
Ideas and Perspectives

Unilateral conditions

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In the case the adhesion is active $\chi > 0$

$$R = \chi \mathbf{u} + \partial I_{]-\infty, 0]}(\mathbf{u} \cdot \mathbf{n}) \mathbf{n}$$

i.e.

- ▶ if $\chi = 0$ we have simply impenetrability conditions
- ▶ if $\chi > 0$ there is a reaction **avoiding separation**

Non-smooth
contact
phenomena and
surface damage

E. Bonetti - M.
Frémond

The model

The physical problem
The damage phenomenon
The adhesion
phenomenon [Frémond
Internal constraints

Unilateral conditions

The PDE system

The PDE: the momentum
balance
The PDE: the evolution of
the damage
(micro-motions)
The PDE: the evolution of
the adhesion
(micro-motions)

Analytical results

Difficulties
Existence result

Asymptotic analysis

The problem
The analysis
Ideas and Perspectives

The PDE: the momentum balance

Non-smooth
contact
phenomena and
surface damage

E. Bonetti - M.
Frémond

We let

Ω smooth and $\Gamma := \partial\Omega = \Gamma_1 \cup \Gamma_2 \cup \Gamma_c$, $t \in (0, T)$

The model

The physical problem
The damage phenomenon
The adhesion
phenomenon [Frémond
Internal constraints
Unilateral conditions

The PDE system

**The PDE: the momentum
balance**

The PDE: the evolution of
the damage
(micro-motions)

The PDE: the evolution of
the adhesion
(micro-motions)

Analytical results

Difficulties
Existence result

Asymptotic analysis

The problem
The analysis
Ideas and Perspectives

The PDE: the momentum balance

Non-smooth
contact
phenomena and
surface damage

E. Bonetti - M.
Frémond

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$$\Omega \text{ smooth and } \Gamma := \partial\Omega = \Gamma_1 \cup \Gamma_2 \cup \Gamma_c, t \in (0, T)$$

We simplify the model taking the displacement u a scalar
(hence ∇u stands for deformation)

$$-\operatorname{div} (K(\beta)\nabla u) = f \quad \text{in } \Omega$$

where: $K(\beta)$ rigidity depending on the damage parameter
 f external volume mechanical action.

The model

The physical problem
The damage phenomenon
The adhesion
phenomenon [Frémond
Internal constraints
Unilateral conditions

The PDE system

**The PDE: the momentum
balance**

The PDE: the evolution of
the damage
(micro-motions)

The PDE: the evolution of
the adhesion
(micro-motions)

Analytical results

Difficulties
Existence result

Asymptotic analysis

The problem
The analysis
Ideas and Perspectives

The PDE: the momentum balance

Non-smooth
contact
phenomena and
surface damage

E. Bonetti - M.
Frémond

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$$-\operatorname{div}(\beta \nabla u) = f \quad \text{in } \Omega$$

where: $K(\beta) = \beta$ degenerates as damage is complete
 $\beta = 0$.

The model

The physical problem
The damage phenomenon
The adhesion
phenomenon [Frémond
Internal constraints
Unilateral conditions

The PDE system

**The PDE: the momentum
balance**

The PDE: the evolution of
the damage
(micro-motions)

The PDE: the evolution of
the adhesion
(micro-motions)

Analytical results

Difficulties
Existence result

Asymptotic analysis

The problem
The analysis
Ideas and Perspectives

The PDE: the momentum balance

Non-smooth
contact
phenomena and
surface damage

E. Bonetti - M.
Frémond

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$$-\operatorname{div}(\beta \nabla u) = f \quad \text{in } \Omega$$

we need some characterization of stress-strain relation
once the damage is complete $\beta = 0$

The model

The physical problem
The damage phenomenon
The adhesion
phenomenon [Frémond
Internal constraints
Unilateral conditions

The PDE system

**The PDE: the momentum
balance**

The PDE: the evolution of
the damage
(micro-motions)

The PDE: the evolution of
the adhesion
(micro-motions)

Analytical results

Difficulties
Existence result

Asymptotic analysis

The problem
The analysis
Ideas and Perspectives

The PDE: the momentum balance

Non-smooth
contact
phenomena and
surface damage

E. Bonetti - M.
Frémond

We let

Ω smooth and $\Gamma := \partial\Omega = \Gamma_1 \cup \Gamma_2 \cup \Gamma_c, t \in (0, T)$

$$-\operatorname{div}(\beta \nabla u + |\nabla u|^2 \nabla u) = f \quad \text{in } \Omega$$

we add a nonlinear elastic term in the stress (residual)

The model

The physical problem
The damage phenomenon
The adhesion
phenomenon [Frémond]
Internal constraints
Unilateral conditions

The PDE system

**The PDE: the momentum
balance**

The PDE: the evolution of
the damage
(micro-motions)

The PDE: the evolution of
the adhesion
(micro-motions)

Analytical results

Difficulties
Existence result

Asymptotic analysis

The problem
The analysis
Ideas and Perspectives

The PDE: the momentum balance

Non-smooth
contact
phenomena and
surface damage

E. Bonetti - M.
Frémond

We let

Ω smooth and $\Gamma := \partial\Omega = \Gamma_1 \cup \Gamma_2 \cup \Gamma_c$, $t \in (0, T)$

the **boundary conditions** for u

$$\begin{aligned} -\operatorname{div}(\beta \nabla u + |\nabla u|^2 \nabla u) &= f \quad \text{in } \Omega, \\ u &= 0 \quad \text{on } \Gamma_1, \quad \sigma \mathbf{n} = \mathbf{g} \quad \text{on } \Gamma_2, \\ \sigma \mathbf{n} + \chi u|_{\Gamma_c} + \partial j_{-\infty, 0]}(u|_{\Gamma_c}) &\ni 0 \quad \text{on } \Gamma_c, \end{aligned}$$

where $\chi u|_{\Gamma_c} + \partial j_{-\infty, 0]}(u|_{\Gamma_c})$ on Γ_c is the reaction

The model

The physical problem
The damage phenomenon
The adhesion phenomenon [Frémond]
Internal constraints
Unilateral conditions

The PDE system

The PDE: the momentum balance

The PDE: the evolution of the damage (micro-motions)
The PDE: the evolution of the adhesion (micro-motions)

Analytical results

Difficulties
Existence result

Asymptotic analysis

The problem
The analysis
Ideas and Perspectives

The PDE: the evolution of the damage (micro-motions)

We consider in Ω

$$\beta_t - \Delta\beta + \partial I_{[0,1]}(\beta) \ni w - \frac{1}{2} |\nabla(u)|^2$$

Non-smooth
contact
phenomena and
surface damage

E. Bonetti - M.
Frémond

The model

The physical problem
The damage phenomenon
The adhesion
phenomenon [Frémond]
Internal constraints
Unilateral conditions

The PDE system

The PDE: the momentum
balance
**The PDE: the evolution of
the damage
(micro-motions)**
The PDE: the evolution of
the adhesion
(micro-motions)

Analytical results

Difficulties
Existence result

Asymptotic analysis

The problem
The analysis
Ideas and Perspectives

The PDE: the evolution of the damage (micro-motions)

Non-smooth contact phenomena and surface damage

E. Bonetti - M. Frémond

We consider in Ω

$$\beta_t - \Delta\beta + \partial I_{[0,1]}(\beta) \ni w - \frac{1}{2}|\nabla(u)|^2$$

where

- ▶ $\partial I_{[0,1]}(\beta) = 0$ if $\beta \in (0, 1)$ and $\partial I_{[0,1]}(0) =]-\infty, 0]$, $\partial I_{[0,1]}(1) = [0, +\infty[$ (a.e. defined) \rightarrow physical constraint
- ▶ $w > 0$ is the cohesion
- ▶ $-\frac{1}{2}|\nabla(u)|^2$ forces $\beta \searrow 0$

The model

The physical problem
The damage phenomenon
The adhesion phenomenon [Frémond
Internal constraints
Unilateral conditions

The PDE system

The PDE: the momentum balance
The PDE: the evolution of the damage (micro-motions)
The PDE: the evolution of the adhesion (micro-motions)

Analytical results

Difficulties
Existence result

Asymptotic analysis

The problem
The analysis
Ideas and Perspectives

The PDE: the evolution of the damage (micro-motions)

Non-smooth contact phenomena and surface damage

E. Bonetti - M. Frémond

We consider in Ω

$$\beta_t - \Delta\beta + \partial I_{[0,1]}(\beta) \ni w - \frac{1}{2} |\nabla(u)|^2$$

with $\partial_n \beta = -\nu(\beta|_{\Gamma_c} - \chi)$ on Γ_c .

- ▶ $\nu(\beta|_{\Gamma_c} - \chi)$ is formally a flux of damage between the body and the glue: it depends on the energy interface coefficient $\nu > 0$

The model

The physical problem
The damage phenomenon
The adhesion phenomenon [Frémond]
Internal constraints
Unilateral conditions

The PDE system

The PDE: the momentum balance
The PDE: the evolution of the damage (micro-motions)
The PDE: the evolution of the adhesion (micro-motions)

Analytical results

Difficulties
Existence result

Asymptotic analysis

The problem
The analysis
Ideas and Perspectives

The PDE: the evolution of the adhesion (micro-motions)

We consider in Γ_c

$$\chi_t - \Delta \chi + \partial I_{[0,1]}(\chi) \ni w_c - \frac{1}{2} |u|_{\Gamma_c}|^2 + \nu(\beta_{|\Gamma_c} - \chi)$$
$$\partial_n \chi = 0, \quad \text{on } \partial \Gamma_c$$

where

- ▶ $\partial I_{[0,1]}(\chi) = 0$ if $\chi \in (0, 1)$ and $\partial I_{[0,1]}(0) =]-\infty, 0]$, $\partial I_{[0,1]}(1) = [0, +\infty[$ (a.e. defined) \rightarrow physical constraint
- ▶ $w_c > 0$ is the cohesion
- ▶ $-\frac{1}{2} |u|_{\Gamma_c}|^2$ forces $\chi \searrow 0$
- ▶ $\nu(\beta_{|\Gamma_c} - \chi)$ is formally a flux of damage between the body and the glue: the damage of the glue increases if $\beta_{|\Gamma_c} - \chi < 0$, i.e. if $\chi > \beta_{|\Gamma_c}$, i.e. the glue is less damaged w.r.t. the domain.

The model

The physical problem
The damage phenomenon
The adhesion
phenomenon [Frémond
Internal constraints
Unilateral conditions

The PDE system

The PDE: the momentum
balance
The PDE: the evolution of
the damage
(micro-motions)
**The PDE: the evolution of
the adhesion
(micro-motions)**

Analytical results

Difficulties
Existence result

Asymptotic analysis

The problem
The analysis
Ideas and Perspectives

The complete PDE system: difficulties

We write the complete PDE system in a variational setting

Non-smooth
contact
phenomena and
surface damage

E. Bonetti - M.
Frémond

The model

The physical problem
The damage phenomenon
The adhesion
phenomenon [Frémond
Internal constraints
Unilateral conditions

The PDE system

The PDE: the momentum
balance
The PDE: the evolution of
the damage
(micro-motions)
The PDE: the evolution of
the adhesion
(micro-motions)

Analytical results

Difficulties
Existence result

Asymptotic analysis

The problem
The analysis
Ideas and Perspectives

The complete PDE system: difficulties

We write the complete PDE system in a variational setting

$$\int_{\Omega} (|\nabla u|^2 \nabla u \cdot \nabla v + \beta \nabla u \cdot \nabla v) + \int_{\Gamma_c} \chi u|_{\Gamma_c} v|_{\Gamma_c} \\ + \int_{\Gamma_c} \partial I_{-}(u|_{\Gamma_c}) v|_{\Gamma_c} = \int_{\Omega} f v + \int_{\Gamma_2} g v,$$

$$v \in W^{1,4}(\Omega), v = 0 \text{ on } \Gamma_1$$

$$\int_{\Omega} (\beta_t \phi + \nabla \beta \cdot \nabla \phi) + \int_{\Omega} \partial I_{[0,1]}(\beta) \phi + \nu \int_{\Gamma_c} (\beta|_{\Gamma_c} - \chi) \phi|_{\Gamma_c} \\ = \int_{\Omega} (w - \frac{1}{2} |\nabla u|^2) \phi, \quad \phi \in H^1(\Omega)$$

$$\chi_t - \Delta \chi + \partial I_{[0,1]}(\chi) \ni w_c - \frac{1}{2} |u|_{\Gamma_c}|^2 + \nu (\beta|_{\Gamma_c} - \chi) \quad \text{in } \Gamma_c$$

→ **non-smooth constraints** on χ , β , and $u|_{\Gamma_c}$

Non-smooth
contact
phenomena and
surface damage

E. Bonetti - M.
Frémond

The model

The physical problem
The damage phenomenon
The adhesion
phenomenon [Frémond]
Internal constraints
Unilateral conditions

The PDE system

The PDE: the momentum
balance
The PDE: the evolution of
the damage
(micro-motions)
The PDE: the evolution of
the adhesion
(micro-motions)

Analytical results

Difficulties
Existence result

Asymptotic analysis

The problem
The analysis
Ideas and Perspectives

The complete PDE system: difficulties

We write the complete PDE system in a variational setting

$$\int_{\Omega} |\nabla u|^2 \nabla u \cdot \nabla v + \beta \nabla u \cdot \nabla v + \int_{\Gamma_c} \chi u|_{\Gamma_c} v|_{\Gamma_c} + \int_{\Gamma_c} \partial I_{-}(u|_{\Gamma_c}) v|_{\Gamma_c} = \int_{\Omega} f u + \int_{\Gamma_2} g v,$$

$$v \in W^{1,4}(\Omega), v = 0 \text{ on } \Gamma_1$$

$$\int_{\Omega} \beta_t \phi + \nabla \beta \cdot \nabla \phi + \int_{\Omega} \partial I_{[0,1]}(\beta) \phi + \nu \int_{\Gamma_c} (\beta|_{\Gamma_c} - \chi) \phi|_{\Gamma_c} = \int_{\Omega} w \phi - \frac{1}{2} |\nabla u|^2 \phi, \quad \phi \in H^1(\Omega)$$

$$\chi_t - \Delta \chi + \partial I_{[0,1]}(\chi) \ni w_c - \frac{1}{2} |u|_{\Gamma_c}|^2 + \nu(\beta|_{\Gamma_c} - \chi) \quad \text{in } \Gamma_c$$

→ quadratic nonlinearities

Non-smooth
contact
phenomena and
surface damage

E. Bonetti - M.
Frémond

The model

The physical problem
The damage phenomenon
The adhesion
phenomenon [Frémond]
Internal constraints
Unilateral conditions

The PDE system

The PDE: the momentum
balance
The PDE: the evolution of
the damage
(micro-motions)
The PDE: the evolution of
the adhesion
(micro-motions)

Analytical results

Difficulties
Existence result

Asymptotic analysis

The problem
The analysis
Ideas and Perspectives

The complete PDE system: difficulties

We write the complete PDE system in a variational setting

$$\int_{\Omega} |\nabla u|^2 \nabla u \cdot \nabla v + \beta \nabla u \cdot \nabla v + \int_{\Gamma_c} \chi u|_{\Gamma_c} v|_{\Gamma_c} + \int_{\Gamma_c} \partial I_{-}(u|_{\Gamma_c}) v|_{\Gamma_c} = \int_{\Omega} fu + \int_{\Gamma_2} gv,$$

$$v \in W^{1,4}(\Omega), v = 0 \text{ on } \Gamma_1$$

$$\int_{\Omega} \beta_t \phi + \nabla \beta \cdot \nabla \phi + \int_{\Omega} \partial I_{[0,1]}(\beta) \phi + \nu \int_{\Gamma_c} (\beta|_{\Gamma_c} - \chi) \phi|_{\Gamma_c} = \int_{\Omega} w \phi - \frac{1}{2} |\nabla u|^2 \phi, \quad \phi \in H^1(\Omega)$$

$$\chi_t - \Delta \chi + \partial I_{[0,1]}(\chi) \ni w_c - \frac{1}{2} |u|_{\Gamma_c}|^2 + \nu(\beta|_{\Gamma_c} - \chi) \quad \text{in } \Gamma_c$$

→ we need **sufficient regularity** on β and u to control their **traces**.

Non-smooth
contact
phenomena and
surface damage

E. Bonetti - M.
Frémond

The model

The physical problem
The damage phenomenon
The adhesion
phenomenon [Frémond]
Internal constraints
Unilateral conditions

The PDE system

The PDE: the momentum
balance
The PDE: the evolution of
the damage
(micro-motions)
The PDE: the evolution of
the adhesion
(micro-motions)

Analytical results

Difficulties
Existence result

Asymptotic analysis

The problem
The analysis
Ideas and Perspectives

The existence theorem

Theorem. Let $T > 0$. Under suitable assumptions on data, there exists a solution (u, χ, β) solving our problem

Non-smooth
contact
phenomena and
surface damage

E. Bonetti - M.
Frémond

The model

The physical problem
The damage phenomenon
The adhesion
phenomenon [Frémond]
Internal constraints
Unilateral conditions

The PDE system

The PDE: the momentum
balance
The PDE: the evolution of
the damage
(micro-motions)
The PDE: the evolution of
the adhesion
(micro-motions)

Analytical results

Difficulties
Existence result

Asymptotic analysis

The problem
The analysis
Ideas and Perspectives

The existence theorem

Theorem. Let $T > 0$. Under suitable assumptions on data, there exists a solution (u, χ, β) solving our problem with

$$u \in L^\infty(0, T; W^{1,4}(\Omega)), \quad u = 0 \text{ a.e. on } \Gamma_1$$

$$\chi \in H^1(0, T; L^2(\Gamma_c)) \cap L^\infty(0, T; H^1(\Gamma_c)) \cap L^2(0, T; H^2(\Gamma_c))$$

$$\beta \in H^1(0, T; L^2(\Omega)) \cap L^\infty(0, T; H^1(\Omega))$$

The model

The physical problem
The damage phenomenon
The adhesion
phenomenon [Frémond]
Internal constraints
Unilateral conditions

The PDE system

The PDE: the momentum
balance
The PDE: the evolution of
the damage
(micro-motions)
The PDE: the evolution of
the adhesion
(micro-motions)

Analytical results

Difficulties
Existence result

Asymptotic analysis

The problem
The analysis
Ideas and Perspectives

Outline

Existence:

- ▶ approximating procedure

**Non-smooth
contact
phenomena and
surface damage**

**E. Bonetti - M.
Frémond**

The model

The physical problem
The damage phenomenon
The adhesion
phenomenon [Frémond
Internal constraints
Unilateral conditions

The PDE system

The PDE: the momentum
balance
The PDE: the evolution of
the damage
(micro-motions)
The PDE: the evolution of
the adhesion
(micro-motions)

Analytical results

Difficulties
Existence result

Asymptotic analysis

The problem
The analysis
Ideas and Perspectives

Outline

Existence:

- ▶ approximating procedure
- ▶ Schauder theorem to solve the approximated problem (theory of evolution equations with maximal monotone operators)

**Non-smooth
contact
phenomena and
surface damage**

**E. Bonetti - M.
Frémond**

The model

The physical problem
The damage phenomenon
The adhesion
phenomenon [Frémond
Internal constraints
Unilateral conditions

The PDE system

The PDE: the momentum
balance
The PDE: the evolution of
the damage
(micro-motions)
The PDE: the evolution of
the adhesion
(micro-motions)

Analytical results

Difficulties
Existence result

Asymptotic analysis

The problem
The analysis
Ideas and Perspectives

Outline

Existence:

- ▶ approximating procedure
- ▶ Schauder theorem to solve the approximated problem (theory of evolution equations with maximal monotone operators)
- ▶ uniform a priori estimates

**Non-smooth
contact
phenomena and
surface damage**

**E. Bonetti - M.
Frémond**

The model

The physical problem
The damage phenomenon
The adhesion
phenomenon (Frémond)
Internal constraints
Unilateral conditions

The PDE system

The PDE: the momentum
balance
The PDE: the evolution of
the damage
(micro-motions)
The PDE: the evolution of
the adhesion
(micro-motions)

Analytical results

Difficulties
Existence result

Asymptotic analysis

The problem
The analysis
Ideas and Perspectives

Outline

Existence:

- ▶ approximating procedure
- ▶ Schauder theorem to solve the approximated problem (theory of evolution equations with maximal monotone operators)
- ▶ uniform a priori estimates
- ▶ passage to the limit by compactness and semicontinuity arguments

Non-smooth
contact
phenomena and
surface damage

E. Bonetti - M.
Frémond

The model

The physical problem
The damage phenomenon
The adhesion
phenomenon (Frémond)
Internal constraints
Unilateral conditions

The PDE system

The PDE: the momentum
balance
The PDE: the evolution of
the damage
(micro-motions)
The PDE: the evolution of
the adhesion
(micro-motions)

Analytical results

Difficulties
Existence result

Asymptotic analysis

The problem
The analysis
Ideas and Perspectives

Outline

Existence:

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Remark.

- ▶ we need some coercive contribution in the equation for u
- ▶ we solve weak versions of the equations in Ω
- ▶ Uniqueness is an open problem

The model

The physical problem
The damage phenomenon
The adhesion phenomenon (Frémond)
Internal constraints
Unilateral conditions

The PDE system

The PDE: the momentum balance
The PDE: the evolution of the damage (micro-motions)
The PDE: the evolution of the adhesion (micro-motions)

Analytical results

Difficulties
Existence result

Asymptotic analysis

The problem
The analysis
Ideas and Perspectives

Asymptotic analysis as $\nu \rightarrow +\infty$

Asymptotic behaviour of solutions as **energy interface coefficient** $\nu \rightarrow +\infty$

Non-smooth contact phenomena and surface damage

E. Bonetti - M. Frémond

The model

The physical problem
The damage phenomenon
The adhesion phenomenon [Frémond]
Internal constraints
Unilateral conditions

The PDE system

The PDE: the momentum balance
The PDE: the evolution of the damage (micro-motions)
The PDE: the evolution of the adhesion (micro-motions)

Analytical results

Difficulties
Existence result

Asymptotic analysis

The problem

The analysis
Ideas and Perspectives

Asymptotic analysis as $\nu \rightarrow +\infty$

Asymptotic behaviour of solutions as **energy interface coefficient** $\nu \rightarrow +\infty$



to investigate properties of the adhesion once the **interaction energy blows up**

$$\Psi_{\Gamma_c} = \dots + \frac{\nu}{2} |\beta|_{\Gamma_c} - \chi|^2$$

Non-smooth contact phenomena and surface damage

E. Bonetti - M. Frémond

The model

The physical problem
The damage phenomenon
The adhesion phenomenon [Frémond]
Internal constraints
Unilateral conditions

The PDE system

The PDE: the momentum balance
The PDE: the evolution of the damage (micro-motions)
The PDE: the evolution of the adhesion (micro-motions)

Analytical results

Difficulties
Existence result

Asymptotic analysis

The problem

The analysis
Ideas and Perspectives

Asymptotic analysis as $\nu \rightarrow +\infty$

Asymptotic behaviour of solutions as **energy interface coefficient** $\nu \rightarrow +\infty$



to investigate properties of the adhesion once the **interaction energy blows up**

$$\Psi_{\Gamma_c} = \dots + \frac{\nu}{2} |\beta|_{\Gamma_c} - \chi|^2$$

From which it follows (in Γ_c) boundary condition

$$\partial_n \beta = -\nu(\beta|_{\Gamma_c} - \chi)$$

and the source (in the adhesion)

$$\chi_t - \Delta \chi + \partial I_{[0,1]}(\chi) \ni w_c - \frac{1}{2} |u|^2 + \nu(\beta|_{\Gamma_c} - \chi)$$

Non-smooth contact phenomena and surface damage

E. Bonetti - M. Frémond

The model

- The physical problem
- The damage phenomenon
- The adhesion phenomenon [Frémond]
- Internal constraints
- Unilateral conditions

The PDE system

- The PDE: the momentum balance
- The PDE: the evolution of the damage (micro-motions)
- The PDE: the evolution of the adhesion (micro-motions)

Analytical results

- Difficulties
- Existence result

Asymptotic analysis

- The problem**
- The analysis
- Ideas and Perspectives

The estimates

We need a priori **estimates** on solutions **not depending on**

ν

**Non-smooth
contact
phenomena and
surface damage**

**E. Bonetti - M.
Frémond**

The model

The physical problem
The damage phenomenon
The adhesion
phenomenon [Frémond
Internal constraints
Unilateral conditions

The PDE system

The PDE: the momentum
balance
The PDE: the evolution of
the damage
(micro-motions)
The PDE: the evolution of
the adhesion
(micro-motions)

Analytical results

Difficulties
Existence result

Asymptotic analysis

The problem
The analysis
Ideas and Perspectives

The estimates

We need a priori **estimates** on solutions **not depending on** $\nu \rightarrow$ the energy and the dissipation of the system turn out to be (weakly) bounded

$$\|u\|_{L^\infty(0,T;W^{1,4}(\Omega))} \leq C$$

$$\|\beta\|_{H^1(0,T;L^2(\Omega)) \cap L^\infty(0,T;H^1(\Omega))} \leq C$$

$$\|\chi\|_{H^1(0,T;L^2(\Gamma_c)) \cap L^\infty(0,T;H^1(\Gamma_c)) \cap L^2(0,T;H^2(\Gamma_c))} \leq C$$

$$\|\beta^{1/2} \nabla u\|_{L^\infty(0,T;L^2(\Omega))} \leq C$$

$$\|\chi^{1/2} u\|_{L^\infty(0,T;L^2(\Gamma_c))} \leq C$$

$$\nu^{1/2} \|\beta - \chi\|_{L^\infty(0,T;L^2(\Gamma_c))} \leq C$$

The model

The physical problem
The damage phenomenon
The adhesion
phenomenon [Frémond]
Internal constraints
Unilateral conditions

The PDE system

The PDE: the momentum
balance
The PDE: the evolution of
the damage
(micro-motions)
The PDE: the evolution of
the adhesion
(micro-motions)

Analytical results

Difficulties
Existence result

Asymptotic analysis

The problem

The analysis

Ideas and Perspectives

The convergence

We have (for subsequences) weak convergences

$$u_\nu \rightarrow u \quad \text{weak star in } L^\infty(0, T; W^{1,4}(\Omega))$$

$$\beta_\nu \rightarrow \beta \quad \text{weak star in } H^1(0, T; L^2(\Omega)) \cap L^\infty(0, T; H^1(\Omega))$$

$$\chi_\nu \rightarrow \chi \quad \text{weak star in}$$

$$H^1(0, T; L^2(\Gamma_c)) \cap L^\infty(0, T; H^1(\Gamma_c)) \cap L^2(0, T; H^2(\Gamma_c))$$

The model

The physical problem
The damage phenomenon
The adhesion
phenomenon (Frémond)
Internal constraints
Unilateral conditions

The PDE system

The PDE: the momentum
balance
The PDE: the evolution of
the damage
(micro-motions)
The PDE: the evolution of
the adhesion
(micro-motions)

Analytical results

Difficulties
Existence result

Asymptotic analysis

The problem
The analysis
Ideas and Perspectives

The convergence

We have (for subsequences) weak convergences

$$u_\nu \rightarrow u \quad \text{weak star in } L^\infty(0, T; W^{1,4}(\Omega))$$

$$\beta_\nu \rightarrow \beta \quad \text{weak star in } H^1(0, T; L^2(\Omega)) \cap L^\infty(0, T; H^1(\Omega))$$

$$\chi_\nu \rightarrow \chi \quad \text{weak star in}$$

$$H^1(0, T; L^2(\Gamma_c)) \cap L^\infty(0, T; H^1(\Gamma_c)) \cap L^2(0, T; H^2(\Gamma_c))$$

and in particular

$$\beta|_{\Gamma_c} = \chi \quad \text{a.e. in } \Gamma_c.$$

The model

The physical problem
The damage phenomenon
The adhesion
phenomenon (Frémond)
Internal constraints
Unilateral conditions

The PDE system

The PDE: the momentum
balance
The PDE: the evolution of
the damage
(micro-motions)
The PDE: the evolution of
the adhesion
(micro-motions)

Analytical results

Difficulties
Existence result

Asymptotic analysis

The problem
The analysis
Ideas and Perspectives

The convergence

We have (for subsequences) weak convergences

$$u_\nu \rightarrow u \quad \text{weak star in } L^\infty(0, T; W^{1,4}(\Omega))$$

$$\beta_\nu \rightarrow \beta \quad \text{weak star in } H^1(0, T; L^2(\Omega)) \cap L^\infty(0, T; H^1(\Omega))$$

$$\chi_\nu \rightarrow \chi \quad \text{weak star in}$$

$$H^1(0, T; L^2(\Gamma_c)) \cap L^\infty(0, T; H^1(\Gamma_c)) \cap L^2(0, T; H^2(\Gamma_c))$$

and in particular

$$\beta|_{\Gamma_c} = \chi \quad \text{a.e. in } \Gamma_c.$$

At the limit the body and the adhesion substance have the same physical properties...

The model

The physical problem
The damage phenomenon
The adhesion phenomenon (Frémond)
Internal constraints
Unilateral conditions

The PDE system

The PDE: the momentum balance
The PDE: the evolution of the damage (micro-motions)
The PDE: the evolution of the adhesion (micro-motions)

Analytical results

Difficulties
Existence result

Asymptotic analysis

The problem
The analysis
Ideas and Perspectives

The passage to the limit in a weak formulation

Non-smooth
contact
phenomena and
surface damage

**E. Bonetti - M.
Frémond**

The model

The physical problem
The damage phenomenon
The adhesion
phenomenon [Frémond
Internal constraints
Unilateral conditions

The PDE system

The PDE: the momentum
balance
The PDE: the evolution of
the damage
(micro-motions)
The PDE: the evolution of
the adhesion
(micro-motions)

Analytical results

Difficulties
Existence result

Asymptotic analysis

The problem
The analysis
Ideas and Perspectives

The passage to the limit in a weak formulation

For all

$$\phi \in L^2(0, T; H^1(\Omega)), \quad \phi \in [0, 1] \text{ a.e.}$$

$$\psi \in L^2(0, T; H^1(\Gamma_c)), \quad \psi \in [0, 1] \text{ a.e.}$$

Non-smooth
contact
phenomena and
surface damage

E. Bonetti - M.
Frémond

The model

The physical problem
The damage phenomenon
The adhesion
phenomenon [Frémond
Internal constraints
Unilateral conditions

The PDE system

The PDE: the momentum
balance
The PDE: the evolution of
the damage
(micro-motions)
The PDE: the evolution of
the adhesion
(micro-motions)

Analytical results

Difficulties
Existence result

Asymptotic analysis

The problem
The analysis
Ideas and Perspectives

The passage to the limit in a weak formulation

$$\begin{aligned} & \int_0^t \int_{\Omega} (\beta_t(\beta - \phi) + \nabla\beta \cdot \nabla(\beta - \phi)) \\ & + \int_0^t \int_{\Omega} (-w(\beta - \phi) + \frac{1}{2}|\nabla u|^2(\beta - \phi)) \\ & + \nu \int_0^t \int_{\Gamma_c} (\beta|_{\Gamma_c} - \chi)(\beta|_{\Gamma_c} - \phi|_{\Gamma_c}) \leq 0 \\ & \int_0^t \int_{\Gamma_c} (\chi_t(\chi - \psi) + \nabla\chi \cdot \nabla(\chi - \psi)) \\ & + \int_0^t \int_{\Gamma_c} (-w_c(\chi - \psi) + \frac{1}{2}|u|_{\Gamma_c}|^2(\chi - \psi)) \\ & + \nu \int_0^t \int_{\Gamma_c} (\chi - \beta|_{\Gamma_c})(\chi - \psi) \leq 0 \end{aligned}$$

Non-smooth
contact
phenomena and
surface damage

E. Bonetti - M.
Frémond

The model

The physical problem
The damage phenomenon
The adhesion
phenomenon [Frémond
Internal constraints
Unilateral conditions

The PDE system

The PDE: the momentum
balance
The PDE: the evolution of
the damage
(micro-motions)
The PDE: the evolution of
the adhesion
(micro-motions)

Analytical results

Difficulties
Existence result

Asymptotic analysis

The problem
The analysis
Ideas and Perspectives

The passage to the limit in a weak formulation

We consider the same test function ϕ for the equation in Ω and in Γ_c :

$$\phi, \quad \psi = \phi|_{\Gamma_c}$$

(ϕ sufficiently regular), with $\phi \in [0, 1]$ a.e.

Non-smooth
contact
phenomena and
surface damage

E. Bonetti - M.
Frémond

The model

The physical problem
The damage phenomenon
The adhesion
phenomenon [Frémond
Internal constraints
Unilateral conditions

The PDE system

The PDE: the momentum
balance
The PDE: the evolution of
the damage
(micro-motions)
The PDE: the evolution of
the adhesion
(micro-motions)

Analytical results

Difficulties
Existence result

Asymptotic analysis

The problem
The analysis
Ideas and Perspectives

The passage to the limit in a weak formulation

Non-smooth
contact
phenomena and
surface damage

E. Bonetti - M.
Frémond

$$\begin{aligned} & \int_0^t \int_{\Omega} (\beta_t(\beta - \phi) + \nabla\beta \cdot \nabla(\beta - \phi)) \\ & + \int_0^t \int_{\Omega} (-w(\beta - \phi) + \frac{1}{2}|\nabla u|^2(\beta - \phi)) \\ & + \nu \int_0^t \int_{\Gamma_c} (\beta|_{\Gamma_c} - \chi)(\beta|_{\Gamma_c} - \phi|_{\Gamma_c}) \leq 0 \\ & \int_0^t \int_{\Gamma_c} (\chi_t(\chi - \phi|_{\Gamma_c}) + \nabla\chi \cdot \nabla(\chi - \phi|_{\Gamma_c})) \\ & + \int_0^t \int_{\Gamma_c} (-w_c(\chi - \phi|_{\Gamma_c}) + \frac{1}{2}|u|_{\Gamma_c}|^2(\chi - \phi|_{\Gamma_c})) \\ & + \nu \int_0^t \int_{\Gamma_c} (\chi - \beta|_{\Gamma_c})(\chi - \phi|_{\Gamma_c}) \leq 0 \end{aligned} \tag{1}$$

The model

The physical problem
The damage phenomenon
The adhesion
phenomenon [Frémond
Internal constraints
Unilateral conditions

The PDE system

The PDE: the momentum
balance
The PDE: the evolution of
the damage
(micro-motions)
The PDE: the evolution of
the adhesion
(micro-motions)

Analytical results

Difficulties
Existence result

Asymptotic analysis

The problem
The analysis
Ideas and Perspectives

The passage to the limit in a weak formulation

Adding we get

$$\begin{aligned} & \int_0^t \int_{\Omega} (\beta_t(\beta - \phi) + \nabla \beta \cdot \nabla(\beta - \phi)) \\ & + \int_0^t \int_{\Omega} (-w(\beta - \phi) + \frac{1}{2} |\nabla u|^2(\beta - \phi)) \\ & + \int_0^t \int_{\Gamma_c} (\chi_t(\chi - \phi|_{\Gamma_c}) + \nabla \chi \cdot \nabla(\chi - \phi|_{\Gamma_c})) \\ & + \int_0^t \int_{\Gamma_c} (-w_c(\chi - \phi|_{\Gamma_c}) + \frac{1}{2} |u|_{\Gamma_c}|^2(\chi - \phi|_{\Gamma_c})) \\ & + \nu \int_0^t \int_{\Gamma_c} (\beta|_{\Gamma_c} - \chi)^2 \leq 0 \end{aligned}$$

Non-smooth
contact
phenomena and
surface damage

E. Bonetti - M.
Frémond

The model

The physical problem
The damage phenomenon
The adhesion
phenomenon [Frémond]
Internal constraints
Unilateral conditions

The PDE system

The PDE: the momentum
balance
The PDE: the evolution of
the damage
(micro-motions)
The PDE: the evolution of
the adhesion
(micro-motions)

Analytical results

Difficulties
Existence result

Asymptotic analysis

The problem
The analysis
Ideas and Perspectives

The passage to the limit in a weak formulation

$$\text{As } \nu \int_0^t \int_{\Gamma_c} (\beta - \chi)^2 \geq 0$$

$$\begin{aligned} & \int_0^t \int_{\Omega} (\beta_t(\beta - \phi) + \nabla \beta \cdot \nabla(\beta - \phi)) \\ & + \int_0^t \int_{\Omega} (-w(\beta - \phi) + \frac{1}{2} |\nabla u|^2(\beta - \phi)) \\ & + \int_0^t \int_{\Gamma_c} (\chi_t(\chi - \phi|_{\Gamma_c}) + \nabla \chi \cdot \nabla(\chi - \phi|_{\Gamma_c})) \\ & + \int_0^t \int_{\Gamma_c} (-w_c(\chi - \phi|_{\Gamma_c}) + \frac{1}{2} |u|_{\Gamma_c}|^2(\chi - \phi|_{\Gamma_c})) \\ & + \nu \int_0^t \int_{\Gamma_c} (\beta|_{\Gamma_c} - \chi)^2 \leq 0 \end{aligned}$$

The model

The physical problem
The damage phenomenon
The adhesion
phenomenon [Frémond
Internal constraints
Unilateral conditions

The PDE system

The PDE: the momentum
balance
The PDE: the evolution of
the damage
(micro-motions)
The PDE: the evolution of
the adhesion
(micro-motions)

Analytical results

Difficulties
Existence result

Asymptotic analysis

The problem
The analysis

Ideas and Perspectives

The passage to the limit

Passing to the limit weakly, as $\beta|_{r_c} = \chi$ a.e. we get

Non-smooth
contact
phenomena and
surface damage

E. Bonetti - M.
Frémond

The model

The physical problem
The damage phenomenon
The adhesion
phenomenon [Frémond
Internal constraints
Unilateral conditions

The PDE system

The PDE: the momentum
balance
The PDE: the evolution of
the damage
(micro-motions)
The PDE: the evolution of
the adhesion
(micro-motions)

Analytical results

Difficulties
Existence result

Asymptotic analysis

The problem
The analysis
Ideas and Perspectives

The passage to the limit

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for any ϕ sufficiently regular

$$\phi \in L^2(0, T; H^{3/2}(\Omega)), \quad \phi = 0 \text{ a.e.}$$

The model

The physical problem
The damage phenomenon
The adhesion
phenomenon [Frémond
Internal constraints
Unilateral conditions

The PDE system

The PDE: the momentum
balance
The PDE: the evolution of
the damage
(micro-motions)
The PDE: the evolution of
the adhesion
(micro-motions)

Analytical results

Difficulties
Existence result

Asymptotic analysis

The problem
The analysis
Ideas and Perspectives

The passage to the limit

Passing to the limit weakly, as $\beta|_{\Gamma_c} = \chi$ a.e. we get

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for any ϕ sufficiently regular

$$\phi \in L^2(0, T; H^{3/2}(\Omega)), \quad \phi = 0 \text{ a.e.}$$

We get a

variational inclusion with **dynamic boundary conditions**

Non-smooth
contact
phenomena and
surface damage

E. Bonetti - M.
Frémond

The model

The physical problem
The damage phenomenon
The adhesion
phenomenon [Frémond
Internal constraints
Unilateral conditions

The PDE system

The PDE: the momentum
balance
The PDE: the evolution of
the damage
(micro-motions)
The PDE: the evolution of
the adhesion
(micro-motions)

Analytical results

Difficulties
Existence result

Asymptotic analysis

The problem
The analysis
Ideas and Perspectives

Ideas and Perspectives

- ▶ modelling **dynamic boundary conditions**
- ▶ concentrating damage energy on a surface: relation to **fractures models?**
- ▶ considering **thermal properties** (inside and on the surface, B. Bonfanti, Rossi, in preparation)
- ▶ asymptotic behaviour as the **adhesion coefficient** $\mu \rightarrow +\infty$ in

$$\Psi = \dots + \frac{\mu}{2} \chi |u|^2$$

- ▶ analysis for **two bodies** $\Omega_1 \cup \Omega_2 \rightarrow$ at the limit we have a unique body Ω with a damage energy concentrated on a surface
- ▶ **Numerical simulation by Freddi, Frémond**

Non-smooth contact phenomena and surface damage

E. Bonetti - M. Frémond

The model

The physical problem
The damage phenomenon
The adhesion phenomenon [Frémond]
Internal constraints
Unilateral conditions

The PDE system

The PDE: the momentum balance
The PDE: the evolution of the damage (micro-motions)
The PDE: the evolution of the adhesion (micro-motions)

Analytical results

Difficulties
Existence result

Asymptotic analysis

The problem
The analysis

Ideas and Perspectives